cetic Your Connection to ICT Research

Local search with OscaR.cbls explained to my neighbor

OscaR v3.0 (Sept 2015)

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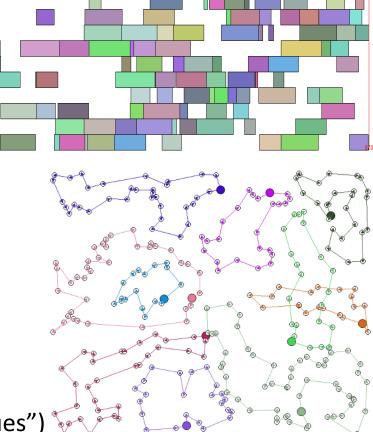
OPERATIONAL RESEARCH IN SCALA





What are optimization problems?

- Scheduling
 - Tasks, precedence's
 - Shared resources
 - Deadlines
- Routing
 - Points, vehicles
 - Distance
 - Time windows
 - Minimize overall distance
- In general
 - Find values (possibly "structured values")
 - Minimizing / optimizing objective (s)
 - Satisfying constraint (s)





Oscar

- Open source framework for combinatorial optimization
- CP, CBLS, MIP, DFO engines
- Open source LGPL license
 - <u>https://bitbucket.org/oscarlib/oscar</u>
 - Implemented in Scala
- Consortium
 - CETIC, UCL, N-Side Belgium
 - Contributions from UPPSALA, Sweden



- Higher credibility
 - Since it is very intricate algorithms, customers can look at the quality of the work
 - Being able to look at the commit activity is also a plus for customers
- Easier transfer
- Mutualise extensions between customers
- Attract contributions
 - From external contributors
 - Find internships



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- Perform a descend in the solution space; repeatedly move from one solution to a better one
- Next solution identified via neighborhood exploration

TSP Example: moving a city to another position in the current circuit

- Current state: $a \rightarrow b \rightarrow c \rightarrow d \rightarrow e \rightarrow a$
- Moving c gives three neighbors:

 $-a \rightarrow c \rightarrow b \rightarrow d \rightarrow e \rightarrow a$

- $-a \rightarrow b \rightarrow d \rightarrow c \rightarrow e \rightarrow a$
- $-a \rightarrow b \rightarrow d \rightarrow e \rightarrow c \rightarrow a$
- O(n²) neighbors in total

• Lots of black magic's, to escape from local minima



Local search–based solver = model + search procedure

Defines variables constraints Objectives

...

Neighborhoods That modify some variables of the problem



Constraint-based local search

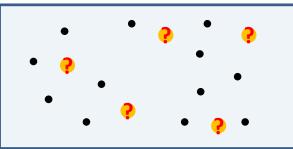
- Goal: make it easy to write optimization engine based on the principle of local search
- Approach: Separate the modeling from the search in different component
 - Represent the problem as a large collection of mathematical formulas
 - Evaluate moves on this formula
- Technically:
 - Have an engine to evaluate the formula quickly
 - Based on the fact that very few decision variables are impacted by a move
 - So rely on incremental model updates



The uncapacitated warehouse location problem

- Given
 - S: set of stores that must be stocked by the warehouses
 - W: set of potential warehouses
 - Each warehouse has a fixed cost ${\rm f}_{\rm w}$
 - transportation cost from warehouse w to store s is c_{ws}
- Find
 - O: subset of warehouses to open
 - Minimizing the sum of the fixed and the transportation cost.

$$\sum_{w \in O} f_w + \sum_{s \in S} \min_{w \in O} (c_{ws})$$



- Notice
 - A store is assigned to its nearest open warehouse



A model of the WLP, written with OscaR.cbls

val m = new Store()

//An array of Boolean variables representing that the warehouse is open or not
val warehouseOpenArray = Array.tabulate(W)
 (w => CBLSIntVar(m, 0 to 1, 0, "warehouse_" + w + ""))

//The set of open warehouses
val openWarehouses = Filter(warehouseOpenArray)

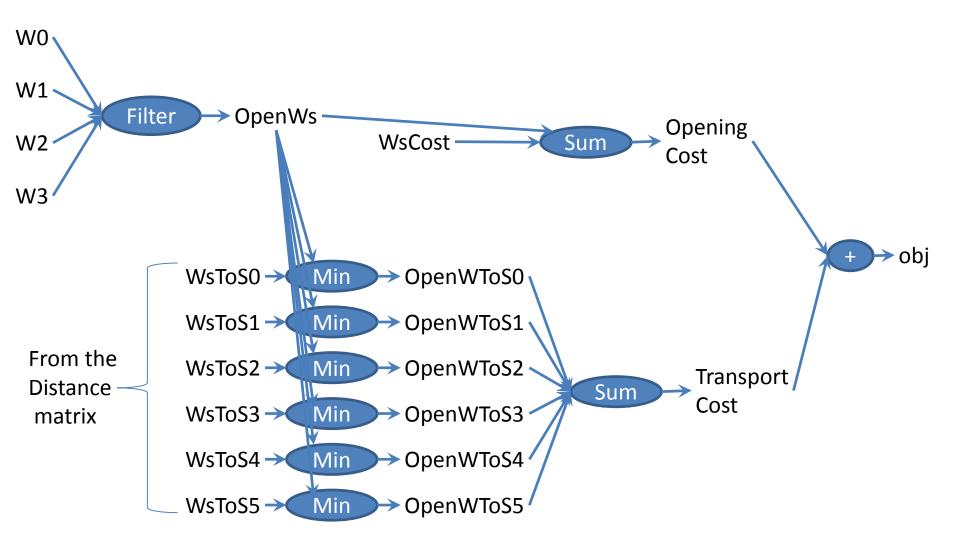
//summing up the distances and the warehouse opening costs
val obj = Objective(Sum(distanceToNearestOpenWarehouse)
 + Sum(costForOpeningWarehouse, openWarehouses))



- Two types of variables
 - IntVar and SetVar
- Invariant library (they are functions, actually)
 - –Logic, such as:
 - Acces on array of IntVar, SetVar
 - Sort
 - Filter, Cluster (indexes of element whose value is...)
 - –MinMax, such as:
 - Min, Max
 - ArgMin, ArgMax
 - –Numeric, such as:
 - Sum, Prod, Minus, Div, Abs
 - -Set, such as:
 - Inter, Union, Diff, Cardinality
 - Summing up to roughly 80 invariants in the library



Propagation graph for the WLP(4,6)





- Model has some input variables
 - warehouseOpenArray
- We can modify the value of these input variables
- The model is updated through a procedure called *propagation*.
 - Propagation is triggered when the value of an output variable is queried, so you always have coherent answers on the model
 - Propagation is very fast, thanks to adequate algorithms and data structures



>println(openWarehouses)
openWarehouses:={}
>println(obj)
IntVarObjective(Sum2:=1500000)

> warehouseOpenArray(0) := 1
> println(openWarehouses)
openWarehouses:={0}
> println(obj)
IntVarObjective(Sum2:=7849)

> warehouseOpenArray(5) := 1
> println(openWarehouses)
openWarehouses:={0,5}
> println(obj)
IntVarObjective(Sum2:=6024)



- Model is fit for local search, based on neighborhood exploration
 - Eg: switching one warehouse (open or close it)
- Does a move improve on the objective?
 - Perform the move Eg: switch the warehouse
 - Query the objective value
 - RollBack
 - Methods available in the Objective class perform this

//summing up the distances and the warehouse opening costs
val obj = Objective(Sum(distanceToNearestOpenWarehouse)
 + Sum(costForOpeningWarehouse, openWarehouses))

- Neighborhood exploration is fast:
 - Propagation is incremental
 - Propagation is not performed after the rollback
 - Partial propagation: only involves what is needed to evaluate obj



- Switching a single warehouse
 - either closing an open warehouse, or opening a closed one
 - Size: O(#W)
 - Connected: all solutions are reachable
- Swapping two warehouses
 - close an open warehouse and open a closed one
 - Size: O(#W²)
 - Not Connected
- Randomization at local minimum
 - Randomize a fraction of the warehouses

How can we assemble these bricks?



- Do all switch moves
- Then all the swap moves
- Iterate until no more moves

We want to try also the random neighborhood choice

- Perform some randomization when minimum reached
- Stop criterion: only two randomizations authorized
- Save the best solution at all time, and restore it when search is finished

Note: the idea of combining neighborhood is not new (eg. [Glo84], [Ml97], and many papers at MIC)



A WLP solver written with neighborhood combinators

val m = new Store()
val warehouseOpenArray = Array.tabulate(W)
 (w => CBLSIntVar(m, 0 to 1, 0, "warehouse_" + w + ""))
val openWarehouses = Filter(warehouseOpenArray)

val obj = Objective(Sum(distanceToNearestOpenWarehouse)
 + Sum(costForOpeningWarehouse, openWarehouses))

m.close()

val neighborhood = (AssignNeighborhood(warehouseOpenArray, "SwitchWarehouse")
 exhaustBack SwapsNeighborhood(warehouseOpenArray, "SwapWarehouses")
 orElse (RandomizeNeighborhood(warehouseOpenArray, W/5) maxMoves 2)
 saveBestAndRestoreOnExhaust obj)

val it = neighborhood.doAllMoves(obj)





WarehouseLocation(W:15, D:150) SwitchWarehouse (warehouse 0:=0 set to 1; objAfter:7052) SwitchWarehouse (warehouse 1:=0 set to 1; objAfter:5346) SwitchWarehouse (warehouse 2:=0 set to 1; objAfter:4961) SwitchWarehouse (warehouse 3:=0 set to 1; objAfter:4176) SwitchWarehouse (warehouse 4:=0 set to 1; objAfter:3862) # SwitchWarehouse (warehouse 9:=0 set to 1; objAfter:3750) # SwitchWarehouse (warehouse 12:=0 set to 1; objAfter:3620) # SwitchWarehouse (warehouse 0:=1 set to 0; objAfter:3609) # SwapWarehouses (warehouse 0:=0 and warehouse 4:=1; objAfter:3572) # SwapWarehouses (warehouse 1:=1 and warehouse 6:=0; objAfter:3552) # SwapWarehouses (warehouse 0:=1 and warehouse 1:=0; objAfter:3532) - # SwitchWarehouse (warehouse 7:=0 set to 1; objAfter:3528) - # RandomizeNeighborhood(warehouse 12:=1 set to 0, warehouse SwitchWarehouse (warehouse 7:=0 set to 1; objAfter:3656) SwapWarehouses (warehouse 12:=0 and warehouse 13:=1; objAfter:3528) RandomizeNeighborhood(warehouse 14:=0 set to 1, warehouse SwitchWarehouse (warehouse 7:=0 set to 1; objAfter:3907) SwitchWarehouse (warehouse 12:=1 set to 0; objAfter:3882) SwitchWarehouse (warehouse 13:=1 set to 0; objAfter:3862) SwitchWarehouse (warehouse 14:=1 set to 0; objAfter:3658) SwitchWarehouse (warehouse 12:=0 set to 1; objAfter:3528) MaxMoves: reached 2 moves openWarehouses:={1,2,3,6,7,9,12}



• The presented one:

val neighborhood = (AssignNeighborhood(warehouseOpenArray, "SwitchWarehouse")
 exhaustBack SwapsNeighborhood(warehouseOpenArray, "SwapWarehouses")
 orElse (RandomizeNeighborhood(warehouseOpenArray, W/5) maxMoves 2)
 saveBestAndRestoreOnExhaust obj)

• Chosing the neighborhood randomly

val neighborhood = (AssignNeighborhood(warehouseOpenArray, "SwitchWarehouse")
 random SwapsNeighborhood(warehouseOpenArray, "SwapWarehouses")
 orElse (RandomizeNeighborhood(warehouseOpenArray, W/5) maxMoves 2)
 saveBestAndRestoreOnExhaust obj)

Learning about neighborhood efficiency

val neighborhood = (AssignNeighborhood(warehouseOpenArray, "SwitchWarehouse")
 learningRandom SwapsNeighborhood(warehouseOpenArray, "SwapWarehouses")
 orElse (RandomizeNeighborhood(warehouseOpenArray, W/5) maxMoves 2)
 saveBestAndRestoreOnExhaust obj)



Conclusion: Features of Oscar.cbls

- Modeling part: Rich modeling language
 - IntVar, SetVar
 - 80 invariants: Logic, numeric, set, min-max, etc.
 - 17 constraints: LE, GE, AllDiff, Sequence, etc.
 - Constraints can attribute a violation degree to any variable
 - Model can include cycles
 - Fast model evaluation mechanism
 - Efficient single wave model update mechanism
 - Partial and lazy model updating, to quickly explore neighborhoods
- Search part
 - Library of standard neighborhoods
 - Combinators to define your global strategy in a concise way
 - Handy verbose and statistics feature, to help you tuning your search
- Business packages: Routing, scheduling
 - Model and neighborhoods
- FlatZinc Front End [Bjö15]
- 27kLOC



• Why don't you use C with templates, and compile with gcc –o3? You would be 2 times faster!

 Why should I use your stuff? I can program a dedicated solver that will run 2 times faster because it will not need the data structures you need in OscaR

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Your Connection to ICT ResearchTo some extend, brain cycle
is more valuable than CPU cycle (2/2)

- That is true, but
 - Algorithmic tunings deliver more than 2 to 4!
 - Ex: We lately had a speedup 10 by tuning a search procedure
 - Using symmetry elimination on neighborhoods
 - Restricting your neighborhood to relevant search zones
 - Our approach cuts down dev cost, so you have time to focus on these high-level tunings.
 - Since budget is always limited
 - Next step: parallel propagation
 - So you will have the same "basic speed" than a dedicated implem, by using more cores
 - A core is cheaper than a single day of work for an engineer



Who is behind OscaR.cbls?

- CETIC team
 - Renaud De Landtsheer
 - Yoann Guyot
 - Christophe Ponsard
 - Gustavo Ospina
- Contributions from Uppsala
 - Jean-Noël Monette
 - Gustav Björdal







Where is OscaR?

- Repository / source code
 - <u>https://bitbucket.org/oscarlib/oscar/wiki/Home</u>
- Released code and documentation
 - <u>https://oscarlib.bitbucket.org/</u>
- Discussion group / mailing list
 - <u>https://groups.google.com/forum/?fromgroups#!foru</u>
 <u>m/oscar-user</u>

Thank you Merci

