

Local search with OscaR.cbls explained to my neighbor

OscaR v3.0 (Sept 2015)

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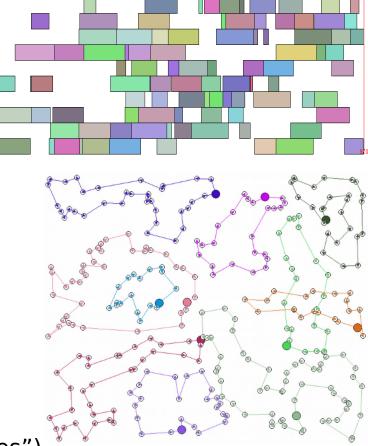
scaR

OPERATIONAL RESEARCH IN SCALA



cetic What are optimization problems?

- Scheduling
 - Tasks, precedence's
 - Shared resources
 - Deadlines
- Routing
 - Points, vehicles
 - Distance
 - Time windows
 - Minimize overall distance
- In general
 - Find values (possibly "structured values")
 - Minimizing / optimizing objective (s)
 - Satisfying constraint (s)





– Oscar

- Open source framework for combinatorial optimization
- CP, CBLS, MIP, DFO engines

Open source LGPL license

- <u>https://bitbucket.org/oscarlib/oscar</u>
- Implemented in Scala

– Consortium

- CETIC, UCL, N-Side Belgium
- Contributions from UPPSALA, Sweden



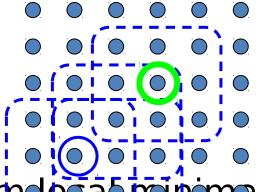
- Higher credibility
 - Since it is very intricate algorithms, customers can look at the quality of the work
 - Being able to look at the commit activity is also a plus for customers
- Easier transfer
- Mutualise extensions between customers
- Attract contributions
 - From external contributors



- Perform a descend in the solution space; repeatedly move from one solution to a better one
- Next solution identified via neighborhood exploration

TSP Example: moving a city to another position in the current circuit

- Current state: a 🛛 b 🗋 c 🗌 d 🗌 e 🗋 a
- Moving c gives three neighbors:
 - a [] **c** [] b [] d [] e [] a
 - a 🛛 b 🗋 d 🗌 **c** 🗌 e 🗌 a
 - a 🗌 b 🗌 d 🗌 e 🗌 **c** 🗌 a



Lots of black magic's, to escape from local minima



al search-based solver = model + search procedur

Defines variables constraints Objectives

. . .

Neighborhoods That modify some variables of the probler



Constraint-based local search

- Goal: make it easy to write optimization engine based on the principle of local search
- Approach: Separate the modeling from the search in different component
 - Represent the problem as a large collection of mathematical formulas
 - Evaluate moves on this formula
- Technically:
 - Have an engine to evaluate the formula quickly
 - Based on the fact that very few decision variables are impacted by a move
 - So rely on incremental model updates



The uncapacitated warehouse location problem

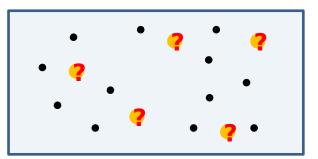
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Given

- urceco – S: set of stores that must be stocked by t^{h} singlesligh
- W: set of potential warehouses
 - Each warehouse has a fixed cost ?
 - transportation cost from w

Find

and the transportation



will show you c will show tion c of the A store is assigned to its nearest open warehouse



A model of the WLP, written with OscaR.cbls

val m = new Store()

//An array of Boolean variables representing that the warehouse is
open or not
val warehouseOpenArray = Array.tabulate(W)
 (w => CBLSIntVar(m, 0 to 1, 0, "warehouse_" + w + ""))

//The set of open warehouses
val openWarehouses = Filter(warehouseOpenArray)

//summing up the distances and the warehouse opening costs
val obj = Objective(Sum(distanceToNearestOpenWarehouse)
 + Sum(costForOpeningWarehouse, openWarehouses))

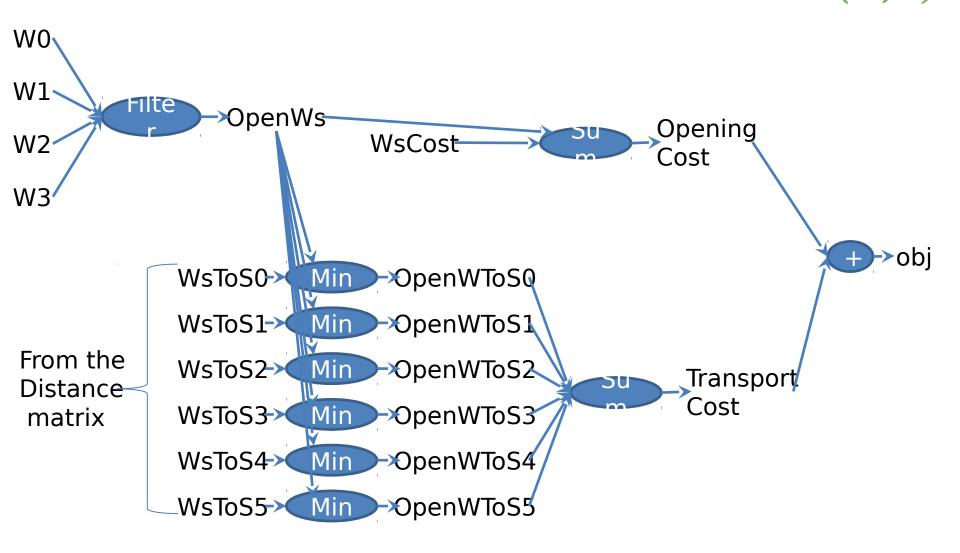


- Two types of variables

 IntVar and SetVar
- Invariant library (they are functions, actually)
 Logic, such as:
 - Acces on array of IntVar, SetVar
 - Sort
 - Filter, Cluster (indexes of element whose value is...)
 - -MinMax, such as:
 - Min, Max
 - ArgMin, ArgMax
 - -Numeric, such as:
 - Sum, Prod, Minus, Div, Abs
 - -Set, such as:
 - Inter, Union, Diff, Cardinality
 - Summing up to roughly 80 invariants in the library



Propagation graph for the WLP(4,6)





- Model has some input variables
 warehouseOpenArray
- We can modify the value of these input variables
- The model is updated through a procedure called *propagation*.
 - Propagation is triggered when the value of an output variable is queried, so you always have coherent answers on the model
 - Propagation is very fast, thanks to adequate algorithms and data structures



Let's play with the model in console

>println(openWarehouses) openWarehouses:={} >println(obj) IntVarObjective(Sum2:=1500000)

> warehouseOpenArray(0) := 1
> println(openWarehouses)
IntVarObjective(Sum2:=7849)
> println(obj)
openWarehouses:={0}

> warehouseOpenArray(5) := 1
> println(openWarehouses)
IntVarObjective(Sum2:=6024)
> println(obj)
openWarehouses:={0.5}



How the model will help optimizing?

- Model is fit for local search, based on neighborhood exploration
 - Eg: switching one warehouse (open or close it)
- Does a move improve on the objective?
 - Perform the move Eg: switch the warehouse
 - Query the objective value
 - RollBack
 - Methods available in the Objective class perform this

//summing up the distances and the warehouse opening costs

val obj =

Objective(Sum(distanceToNearestOpenWarehouse)

- Neighborhood @xpitraflorn/isglastehouse, openWarehouses)) Propagation is incremental

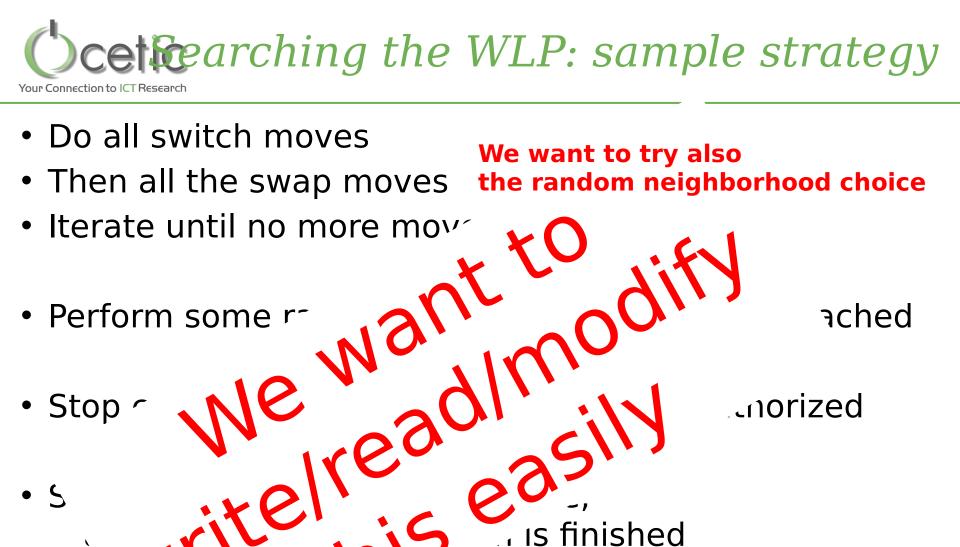
 - Propagation is not performed after the rollback
 - Partial propagation: only involves what is needed to evaluate obj



- Switching a single warehouse

 either closing an open warehouse, or opening a closed one
 - Size: O(#W)
 - Connected: all solutions are reachable
- Swapping two warehouses
 - close an open warehouse and open a closed one
 - Size: O(#W²)
 - Not Connected
- Randomization at local minimum
 Randomize a fraction of the warehouses

How can we assemble these bricks?



Note: t

(eg. [G



A WLP solver written with neighborhood combinators

val m = new Store()
val warehouseOpenArray = Array.tabulate(W)
 (w => CBLSIntVar(m, 0 to 1, 0, "warehouse_" + w + ""))
val openWarehouses = Filter(warehouseOpenArray)

val obj = Objective(Sum(distanceToNearestOpenWarehouse)
 + Sum(costForOpeningWarehouse, openWarehouses))

m.close()



The console output

WarehouseLocation(W:15, D:150) SwitchWarehouse(warehouse 0:=0 set to 1; objAfter:7052) - # SwitchWarehouse(warehouse 1:=0 set to 1; objAfter:5346) # SwitchWarehouse(warehouse 2:=0 set to 1; objAfter:4961) # SwitchWarehouse(warehouse_3:=0 set to 1; objAfter:4176) # SwitchWarehouse(warehouse_4:=0 set to 1; objAfter:3862) # SwitchWarehouse(warehouse_9:=0 set to 1; objAfter:3750) # SwitchWarehouse(warehouse 12:=0 set to 1; objAfter:3620) # SwitchWarehouse(warehouse 0:=1 set to 0; objAfter:3609) - # SwapWarehouses(warehouse_0:=0 and warehouse_4:=1; objAfter:3572) - # SwapWarehouses(warehouse 1:=1 and warehouse 6:=0; objAfter:3552) - # SwapWarehouses(warehouse_0:=1 and warehouse_1:=0; objAfter:3532) - # SwitchWarehouse(warehouse 7:=0 set to 1; objAfter:3528) - # RandomizeNeighborhood(warehouse 12:=1 set to 0, warehouse SwitchWarehouse(warehouse_7:=0 set to 1; objAfter:3656) - ° SwapWarehouses(warehouse 12:=0 and warehouse 13:=1; objAfter:3528) RandomizeNeighborhood(warehouse 14:=0 set to 1, warehouse SwitchWarehouse(warehouse 7:=0 set to 1; objAfter:3907) SwitchWarehouse(warehouse_12:=1 set to 0; objAfter:3882) SwitchWarehouse(warehouse_13:=1 set to 0; objAfter:3862) SwitchWarehouse(warehouse_14:=1 set to 0; objAfter:3658) SwitchWarehouse(warehouse_12:=0 set to 1; objAfter:3528) MaxMoves: reached 2 moves openWarehouses:={1,2,3,6,7,9,12}



• The presented one:

val neighborhood = (AssignNeighborhood(warehouseOpenArray, "SwitchWarehouse")

exhaustBack SwapsNeighborhood(warehouseOpenArray,

"SwapWarehouses")

orElse (RandomizeNeighborhood(warehouseOpenArray, W/5) marhoeingthe neighborhood randomly saveBestAndRestoreOnExhaust obj)

val neighborhood = (AssignNeighborhood(warehouseOpenArray, "SwitchWarehouse")

random SwapsNeighborhood(warehouseOpenArray,

"SwapWarehouses")

• Learningsaboutimeighborhood-efficiency⁵⁾ maxMoves 2)

val neigne Bastand Restgra Qn Exbausta (WarehouseOpenArray, "SwitchWarehouse")

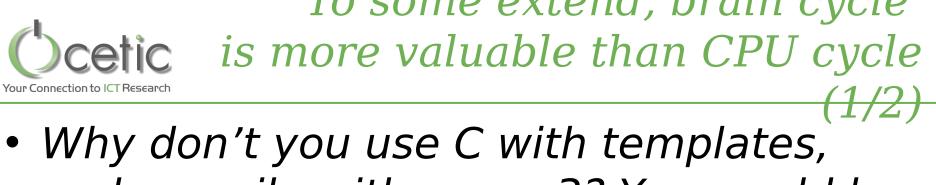
learningRandom SwapsNeighborhood(warehouseOpenArray, "SwapWarehouses")

orElse (RandomizeNeighborhood(warehouseOpenArray, W/5) maxMoves 2)



Conclusion: Features of Oscar.cbls

- Modeling part: Rich modeling language
 - IntVar, SetVar
 - 80 invariants: Logic, numeric, set, min-max, etc.
 - 17 constraints: LE, GE, AllDiff, Sequence, etc.
 - Constraints can attribute a violation degree to any variable
 - Model can include cycles
 - Fast model evaluation mechanism
 - Efficient single wave model update mechanism
 - Partial and lazy model updating, to quickly explore neighborhoods
- Search part
 - Library of standard neighborhoods
 - Combinators to define your global strategy in a concise way
 - Handy verbose and statistics feature, to help you tuning your search
- Business packages: Routing, scheduling
 - Model and neighborhoods
- FlatZinc Front End [Bjö15]
- 27kLOC



- Why don't you use C with templates, and compile with gcc -o3? You would be 2 times faster!
- Why should I use your stuff? I can program a dedicated solver that will run 2 times faster because it will not need the data structures you need in OscaR



is more valuable than CPU cycle

- That is true, but
 - Algorithmic tunings deliver more than 2 to 4!
 - Ex: We lately had a speedup 10 by tuning a search procedure
 - Using symmetry elimination on neighborhoods
 - Restricting your neighborhood to relevant search zones
 - Our approach cuts down dev cost, so you have time to focus on these high-level tunings.
 - Since budget is always limited
 - Next step: parallel propagation
 - So you will have the same "basic speed" than a dedicated implem, by using more cores
 - A core is cheaper than a single day of work for an engineer



Who is behind OscaR.cbls?

- CETIC team
 - Renaud De Landtsheer
 - Yoann Guyot
 - Christophe Ponsard
 - Gustavo Ospina
- Contributions from Uppsala
 - Jean-Noël Monette
 - Gustav Björdal







Where is OscaR?

- Repository / source code
 - <u>https://bitbucket.org/oscarlib/oscar/wiki/Ho</u>
 <u>me</u>
- Released code and documentation

 <u>https://oscarlib.bitbucket.org/</u>
- Discussion group / mailing list
 - <u>https://groups.google.com/forum/?fromgrou</u> <u>ps#!forum/oscar-user</u>

Thank you Merci

